

# COMPARISON OF BROWNIAN JUMP AND BROWNIAN BRIDGE RESETTING IN SEARCH FOR GAUSSIAN TARGET ON THE LINE AND IN SPACE

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**ABSTRACT.** We consider a Brownian searcher with diffusion coefficient  $D$  in  $d$ -dimensions, for  $d = 1, 2, 3$ , that starts from the origin and searches for a random target with a centered-Gaussian distribution. The searcher is also equipped with a resetting mechanism that resets the searcher back to the origin. We consider three different resetting mechanisms. One is a Poissonian reset with rate  $r$  whereby at the reset time the searcher instantaneously jumps back to the origin, one is a periodic reset with period  $T$  whereby at the reset time the searcher instantaneously jumps back to the origin, and one is a Brownian bridge reset with period  $T$ , whereby the Brownian motion is conditioned to return to the origin at time  $T$ . Unlike the first two search processes, this last one has continuous paths. For  $d = 1$  and  $d = 3$ , we obtain analytic formulas for the expected time to locate the random target, and minimize them over  $r$  or  $T$ , as the case may be. In one dimension, this expected time scales as  $\frac{\sigma^2}{D}$ , which is not surprising, but in three dimensions we obtain the anomalous scaling  $\frac{\sigma^3}{D}$ . We compare the relative efficiencies of the three search processes. In two dimensions, we show that the expected time scales as  $\frac{\sigma^2}{D}$  for the Poissonian reset mechanism.

## 1. INTRODUCTION AND STATEMENT OF RESULTS

The use of resetting in search problems is a common phenomenon in various contexts. For example, in everyday life, one might be searching for some target, such as a face in a crowd or a misplaced object. After having searched unsuccessfully for a while, there is a tendency to return to the starting point and begin the search anew. Other contexts where search problems frequently involve resetting include animal foraging [1, 26] and internet search algorithms.

Over the past decade or so, a variety of stochastic processes with resetting have attracted much attention. See [13] for a rather comprehensive, recent overview. Prominent among such processes is the diffusive search

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process with instantaneous resetting, which we now describe. Consider a target located at  $a \in \mathbb{R}^d$ ,  $d \geq 1$ , and consider a search process that sets off from the origin and performs  $d$ -dimensional Brownian motion with diffusion coefficient  $D > 0$ , which is fixed once and for all. Throughout the paper, we suppress the dependence on  $D$  in our notation. The search process is also equipped with an exponential clock with rate  $r$ , so that if it has failed to locate the target by the time the clock rings, then its position is instantaneously reset to the origin and it continues its search anew independently with the same rule. See, for example, [9, 11] for details of the construction of the process. We consider  $r$  as a parameter that can be varied. In dimension one, the target is considered “located” when the process hits the point  $a$ . In dimensions two and higher, since the probability of a Brownian motion ever hitting a particular point is zero, one chooses an  $\epsilon_0 > 0$  which is fixed once and for all, and the target is considered “located” when the process hits the  $\epsilon_0$ -ball centered at  $a$ .

Denote the search process by  $X^{(d;r)}(\cdot)$  and let  $P_0^{(d;r)}$  and  $E_0^{(d;r)}$  denote probabilities and expectations for the process starting from 0. Let

$$(1.1) \quad \tau_a = \begin{cases} \inf\{t \geq 0 : X^{(1;r)}(t) = a\}, & d = 1; \\ \inf\{t \geq 0 : |X^{(d;r)}(t) - a| \leq \epsilon_0\}, & d \geq 2 \end{cases}$$

denote the time at which a target at  $a \in \mathbb{R}^d$  is located. Throughout the paper, we suppress the dependence on  $\epsilon_0$  in the notation. For the above search process, as well as for other related models, quite a number of papers have investigated a number of phenomena, in particular, the expected time to reach the target,  $E_0^{(d;r)}\tau_a$ , the probability of not locating the target for large time,  $P_0^{(d;r)}(\tau_a > t)$  for large  $t$ , and the stationary probability measure for the process. See, for example, [9, 10, 11, 12, 19, 18, 8, 24].

The resetting in the above model is of course discontinuous—at the ring of the exponential clock, the search process instantaneously jumps back to its initial position at the origin. In certain applications, this may be a realistic assumption, but in many others, it is more realistic to consider a type of resetting for which the search process remains continuous. For example, while the instantaneous jump model might be reasonable for an internet search, a continuous type of resetting would be more realistic for animal foraging. A number of very recent papers have addressed this issue, using deterministic return processes, sometimes with constant velocity in the direction of the reset point, and sometimes with other regimes [5], [17],[20], [6]. In these papers, in order to make the problem more tractable mathematically, the

target is not allowed to be discovered during the return process. These papers study, in particular, the stationary probability distribution for these processes as well as the expected time to reach the target at  $a \in \mathbb{R}^d$ .

In this paper, we introduce a continuous search process with resetting via the Brownian bridge. The Brownian bridge with time interval  $T$ , which we describe in more detail below, is a Brownian motion conditioned to return to its starting point at time  $T$ . The search process, which we call the Brownian bridge reset search process with time interval  $T$ , performs one Brownian bridge with time interval  $T$  after the other, until it locates the target. Unlike the continuous models in the papers cited in the above paragraph, this model does not have a search regime with its own parameters, followed by a return regime with its own parameters. Rather, there is one seamless process which searches and returns with two parameters throughout; namely, the diffusion coefficient  $D$  and the time interval  $T$ . Furthermore, unlike in the above models, the target may be located at any time. (We note that a recent paper [7] introduced a hybrid version of the above two search processes in the one-dimensional case. The process in that paper is the search process with instantaneous resetting, conditioned to return to the origin at time  $T$ . The authors study various properties of this process on the time interval  $[0, T]$ .)

Most of the papers in the literature deal with the expected hitting time of a fixed target  $a$ , rather than a random target, although we note that the early paper [10] does consider random targets. Of course, once one has a formula for the expected hitting time of a fixed target, the formula for a random target is obtained simply by integration. However, we are interested in optimizing the parameters to obtain the smallest possible hitting time. In order to understand the scaling and to obtain numerically the optimal hitting time, one needs to express the integrated expected hitting time in a reasonably nice closed form. In this paper we will study the expected hitting time of a random target  $a \in \mathbb{R}^d$  that is distributed according to a Gaussian distribution centered at the origin, the point to which the search process is reset. Our choice of centered Gaussian distributions has been dictated by a combination of what would be interesting and natural, and by what will lend itself to closed form formulas. (We note that for the case of instantaneous resetting, a recent paper [23] studied the behavior of the probability of not locating a random target for large time, where the target comes from a rather wide family of symmetric distributions, including Gaussian distributions.)

We wish to compare the efficiency of the Brownian bridge reset search process, with its parameters  $D$  and  $T$ , to the instantaneous reset search process described above, with its parameters  $D$  and  $r$ , where efficiency is measured by the infimum of the expected value of the search time, the

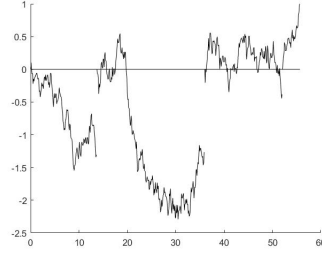
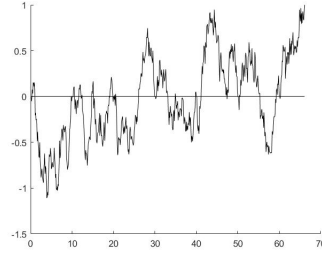
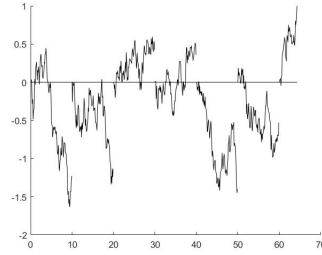
infimum being taken over  $T$  and over  $r$  respectively for the two processes. This leads us naturally to consider also a third search process, as we now explain.

The instantaneous reset search process and the Brownian bridge reset search process are both Markov processes, but there is one fundamental difference between them; namely the instantaneous process is time-homogeneous while the Brownian bridge reset search process is time-inhomogeneous, with cyclic time-inhomogeneity of period  $T$ . It seems that there is no way around the time-inhomogeneity of the Brownian bridge reset search process. However, we can easily change the instantaneous process from time homogeneous to time-inhomogeneous with cyclic time-inhomogeneity of period  $T$ . Indeed, instead of using an exponential clock with rate  $r$  to determine when the process jumps back to its starting point, we simply let it jump back to its starting point every  $T$  units of time.

From now on, in order to fall in line with rather prevalent terminology in the literature, we will refer to the original instantaneous reset search process, with parameters  $D$  and  $r$ , as the Poissonian instantaneous reset search process, and we will refer to the instantaneous reset search process described in the previous paragraph, with parameters  $D$  and  $T$ , as the periodic instantaneous reset search process.

Denote the Brownian bridge reset search process by  $X^{\text{bb},d;T}(\cdot)$  and let  $P_0^{\text{bb},d;T}$  and  $E_0^{\text{bb},d;T}$  denote probabilities and expectations for process starting from 0. Denote the periodic instantaneous reset search process by  $X^{d;T}(\cdot)$  and let  $P_0^{d;T}$  and  $E_0^{d;T}$  denote probabilities and expectations for the process starting from 0. We have already established notation for the Poissonian instantaneous reset search process. Note that the only difference in notation between the Poissonian and the periodic instantaneous reset search processes is the use of  $T$  versus  $r$ . For the Brownian bridge reset search process and the periodic instantaneous reset search process, we use the same notation,  $\tau_a$ , as was used for the Poissonian reset search process for the time to locate the target. Thus, for these two processes,  $\tau_a$  is defined as in (1.1), but with  $X^{d;r}$  replaced by  $X^{\text{bb},d;T}$  or by  $X^{d;T}$ . Before we state our results, we define rigorously the two search processes  $X^{\text{bb},d;T}(\cdot)$  and  $X^{d;T}(\cdot)$ .

As above, fix once and for all the diffusion coefficient  $D > 0$ . Recall that the one-dimensional Brownian bridge with bridge time interval  $T$  is the one-dimensional Brownian motion conditioned to be at the origin at time  $T$ . For background on this process, see for example, [16, 25]. As is well-known [16, 25], a one-dimensional Brownian bridge with bridge time interval  $T$  and diffusion coefficient  $D$  can be represented as  $(W(t) - \frac{t}{T}W(T))$ ,  $0 \leq t \leq T$ , where  $W(\cdot)$  is a one-dimensional Brownian motion with diffusion coefficient  $D$ . The  $d$ -dimensional Brownian bridge with bridge time interval

FIGURE 1. Poissonian instantaneous reset;  $r = \frac{1}{10}$ ,  $a = 1$ FIGURE 2. Brownian bridge reset;  $T = 10$ ,  $a = 1$ FIGURE 3. Periodic instantaneous reset;  $T = 10$ ,  $a = 1$ 

$T$  and diffusion coefficient  $D$  is the process in  $\mathbb{R}^d$  whose components are independent one-dimensional Brownian bridges with bridge time interval  $T$  and diffusion coefficient  $D$ . For  $T > 0$ , let  $\{B_n^{\text{bb},d;T}(t), 0 \leq t \leq T\}_{n=1}^\infty$  be a sequence of independent  $d$ -dimensional Brownian bridges with bridge time interval  $T$  and diffusion coefficient  $D$ . Define the Brownian bridge reset search process  $X^{\text{bb},d;T}(\cdot)$  by

$$(1.2) \quad X^{\text{bb},d;T}(t) = B_n^{\text{bb},d;T}(t - nT), \quad t \in [nT, (n+1)T), \quad n = 0, 1, 2, \dots$$

Similarly, let  $\{B_n^d(t), 0 \leq t \leq T\}_{n=1}^\infty$  be a sequence of independent  $d$ -dimensional Brownian motions with diffusion coefficient  $D$ . Define the periodic instantaneous reset search process  $X^{d;T}(\cdot)$  by

$$(1.3) \quad X^{d;T}(\cdot) = B_n^d(t - nT), \quad t \in [nT, (n+1)T), \quad n = 0, 1, 2, \dots$$

For the processes  $X^{\text{bb},d;T}$  and  $X^{d;T}$ , we consider  $T$ , the time interval between resets, to be a parameter that can be varied, just as we consider the rate  $r$  of the exponential clock a parameter that can be varied for the process  $X^{d;r}$ . Figures 1-3 present a simulation for each of the three search processes with target  $a = 1$ .

Let  $\mu_{\sigma^2}^{\text{Gauss},d}$  denote the centered Gaussian distribution on  $\mathbb{R}^d$  with variance  $\sigma^2$ . Under the three search processes we have defined, we wish to calculate the expected time to locate the target; namely,

$$(1.4) \quad \begin{aligned} & \int_{\mathbb{R}^d} E_0^{d;r} \tau_a \mu_{\sigma^2}^{\text{Gauss},d}(da), \quad \int_{\mathbb{R}^d} E_0^{\text{bb},d;T} \tau_a \mu_{\sigma^2}^{\text{Gauss},d}(da) \\ & \text{and} \quad \int_{\mathbb{R}^d} E_0^{d;T} \tau_a \mu_{\sigma^2}^{\text{Gauss},d}(da). \end{aligned}$$

Then we compare the efficiency of the processes by calculating the infimum (over  $T$  or  $r$  as appropriate) of the above expected time to locate the target.

Of course, the first step is to evaluate  $E_0^{d;r} \tau_a$ ,  $E_0^{\text{bb},d;T} \tau_a$  and  $E_0^{d;T} \tau_a$ , for fixed  $a$ . Expressions for  $E_0^{d;r} \tau_a$  and  $E_0^{d;T} \tau_a$  appear in the literature, as will be noted in sections 2 and 4. It turns out that in dimensions  $d = 1$  and  $d = 3$ , closed form formulas or close to closed form formulas exist for these expressions. We will show in this paper that the same is true for  $E_0^{\text{bb},d;T} \tau_a$ . A reasonably closed form formula in dimension  $d = 2$  is known for the first of these three expressions. As will be seen below in sections 3 and 4, in order to get reasonably nice formulas for the second and third expressions, one needs to have a reasonably nice formula for the probability density of  $\tau_a$  under standard  $d$ -dimensional Brownian motion (actually, sub-density in dimensions  $d \geq 3$ , since in these dimensions  $\tau_a = \infty$  with positive probability). One can obtain this density (or sub-density, as the case may be) from Theorem 2.2 in [15]. Whereas the formula is nice in dimensions one and three, it is quite unwieldy in dimension two. In light of this, we are able to calculate in a reasonably explicit way all three expressions in (1.4) in dimensions  $d = 1$  and  $d = 3$ , but only the first of these three expressions in dimension  $d = 2$ . Thus, in the sequel, these will be the expressions we study.

The results for the above expectations for fixed  $a$  will be presented in sections 2–4. It turns out that  $E_0^{d;r} \tau_a$  grows exponentially in  $a$ , thus the corresponding expression in (1.4) is finite for all choices of  $D, r$  and  $\sigma^2$ . However, each of the other two expectations grows on the order  $e^{C(D,T)a^2}$

for an appropriate constant  $C(D, T)$ , and as will be seen, the corresponding expressions in (1.4) are finite only for appropriate values of  $D, T$  and  $\sigma^2$ . (We note that [22] considered a Poissonian instantaneous reset process in one-dimension in which the exponential reset clock is replaced by a spatially dependent clock. By appropriate choice of the spatial dependence, it is shown there that the expected value of  $\tau_a$  can be made to grow on the order  $|a|^{2+\delta}$ , for any  $\delta > 0$ .)

As will be seen, with regard to the parameter  $D$ , the diffusion coefficient of the search process, and the parameter  $\sigma^2$ , the variance of the target distribution, in dimension  $d = 1$ , all three expressions in (1.4) scale in a standard way; namely as  $\frac{\sigma^2}{D}$ . However, in dimension  $d = 3$ , we obtain the anomalous scaling  $\frac{\sigma^3}{D}$ . This, of course, leads one to wonder what scaling occurs in dimension  $d = 2$ . We will show that in dimension  $d = 2$ , the first expression in (1.4) has the standard scaling obtained in the one-dimensional case. Indeed, this renders the scaling obtained in the three-dimensional case all the more anomalous.

We now state our main results; namely, the explicit calculations of the expressions in (1.4) and the corresponding infima over  $r$  or  $T$ , as appropriate, for dimensions  $d = 1$  and  $d = 3$ , and also for dimension  $d = 2$  in the case of the first of the three expressions in (1.4). We begin with the one-dimensional case. Here is the result for the Poissonian instantaneous reset search process.

**Theorem 1.**

$$(1.5) \quad \int_{\mathbb{R}} (E_0^{(1;r)} \tau_a) \mu_{\sigma^2}^{Gauss,1}(da) = \frac{1}{r} \left( 2e^{\frac{r\sigma^2}{D}} \int_{-\sqrt{\frac{2r}{D}}\sigma}^{\infty} \frac{e^{-\frac{x^2}{2}}}{\sqrt{2\pi}} dx - 1 \right).$$

Equivalently, writing  $r = \frac{D}{\sigma^2}s$ , with  $s > 0$ ,

$$(1.6) \quad \int_{\mathbb{R}} (E_0^{(1;\frac{D}{\sigma^2}s)} \tau_a) \mu_{\sigma^2}^{Gauss,1}(da) = \frac{\sigma^2}{D} \left( \frac{2e^s \int_{-\sqrt{2}s}^{\infty} \frac{e^{-\frac{x^2}{2}}}{\sqrt{2\pi}} dx - 1}{s} \right).$$

One has

$$(1.7) \quad \inf_{r>0} \int_{\mathbb{R}} (E_0^{(1;r)} \tau_a) \mu_{\sigma^2}^{Gauss,1}(da) \approx 3.548 \frac{\sigma^2}{D} \quad \text{with the infimum attained at } r \approx 0.491 \frac{D}{\sigma^2}.$$

Here is the corresponding result for the Brownian bridge reset search process.

**Theorem 2.**

$$(1.8) \quad \int_{\mathbb{R}} (E_0^{bb,1;T} \tau_a) \mu_{\sigma^2}^{Gauss,1}(da) = \begin{cases} T \left( \frac{DT}{DT-4\sigma^2} \right)^{\frac{1}{2}} - T + \frac{T\sigma}{\sqrt{DT+2\sigma}}, & T > \frac{4\sigma^2}{D}; \\ \infty, & T \leq \frac{4\sigma^2}{D}. \end{cases}$$

Equivalently, writing  $T = \frac{\sigma^2}{D}\mathcal{T}$ , with  $\mathcal{T} > 0$ ,

(1.9)

$$\int_{\mathbb{R}} (E_0^{bb,1;\frac{\sigma^2}{D}\mathcal{T}} \tau_a) \mu_{\sigma^2}^{Gauss,1}(da) = \begin{cases} \frac{\sigma^2}{D} \left( \mathcal{T} \left( \frac{\mathcal{T}}{\mathcal{T}-4} \right)^{\frac{1}{2}} - \mathcal{T} + \frac{\mathcal{T}}{2+\sqrt{\mathcal{T}}} \right), & \mathcal{T} > 4; \\ \infty, & \mathcal{T} \leq 4. \end{cases}$$

One has

(1.10)

$$\inf_{T>0} \int_{\mathbb{R}} (E_0^{bb,1;T} \tau_a) \mu_{\sigma^2}^{Gauss,1}(da) \approx 4.847 \frac{\sigma^2}{D} \text{ with the infimum attained at } T \approx 10.136 \frac{\sigma^2}{D}.$$

And here is the corresponding result for the periodic instantaneous reset search process.

**Theorem 3.**

(1.11)

$$\int_{\mathbb{R}} (E_0^{(1;T)} \tau_a) \mu_{\sigma^2}^{Gauss,1}(da) = \begin{cases} \frac{2}{\sqrt{2\pi}} \int_0^T \frac{\int_0^t \frac{1}{t^{\frac{1}{2}}} e^{-\frac{\sigma^2 x^2}{2Dt}} dt}{\int_0^T \frac{1}{t^{\frac{1}{2}}} e^{-\frac{\sigma^2 x^2}{2Dt}} dt} e^{-\frac{x^2}{2}} dx + T \left( \frac{2\sqrt{D}}{\sigma} \int_0^\infty \frac{1}{\int_0^T \frac{x}{s^{\frac{1}{2}}} e^{-\frac{\sigma^2 x^2}{2Ds}} ds} e^{-\frac{x^2}{2}} dx - 1 \right), & T > \frac{\sigma^2}{D}; \\ \infty, & T \leq \frac{\sigma^2}{D}. \end{cases}$$

Equivalently, writing  $T = \frac{\sigma^2}{D}\mathcal{T}$ , with  $\mathcal{T} > 0$ ,

(1.12)

$$\int_{\mathbb{R}} (E_0^{(1;\frac{\sigma^2}{D}\mathcal{T})} \tau_a) \mu_{\sigma^2}^{Gauss,1}(da) = \begin{cases} \frac{\sigma^2}{D} \left( \frac{2}{\sqrt{2\pi}} \int_0^\infty \frac{\int_0^\mathcal{T} \frac{1}{s^{\frac{1}{2}}} e^{-\frac{x^2}{2s}} ds}{\int_0^\mathcal{T} \frac{1}{s^{\frac{1}{2}}} e^{-\frac{x^2}{2s}} ds} e^{-\frac{x^2}{2}} dx + 2\mathcal{T} \int_0^\infty \frac{1}{\int_0^\mathcal{T} \frac{x}{s^{\frac{1}{2}}} e^{-\frac{x^2}{2s}} ds} e^{-\frac{x^2}{2}} dx - \mathcal{T} \right), & \mathcal{T} > 1, \\ \infty, & \mathcal{T} \leq 1. \end{cases}$$

One has

(1.13)

$$\inf_{T>0} \int_{\mathbb{R}} (E_0^{(1;T)} \tau_a) \mu_{\sigma^2}^{Gauss,1}(da) \approx 3.35 \frac{\sigma^2}{D} \text{ with the infimum attained at } T \approx 2.82 \frac{\sigma^2}{D}.$$

**Conclusion for the one-dimensional case.** From Theorems 1–3, it follows that the appropriate scaling unit for the resetting rate  $r$  in the case of the Poissonian instantaneous reset search process is  $\frac{D}{\sigma^2}$ , and the appropriate scaling unit for the time interval  $T$  in the case of the Brownian bridge reset search process and the periodic instantaneous reset search process is  $\frac{\sigma^2}{D}$ . In all of these cases, the corresponding expected time to locate the target is an appropriate constant times  $\frac{\sigma^2}{D}$ . This is a natural and expected scaling.



Comparing the two time-inhomogeneous processes, one with instantaneous jump resetting and one with continuous resetting via the Brownian bridge, one sees from (1.10) and (1.13) that the optimal expected time to locate the target is about 37 percent longer for the continuous search process than for the one with instantaneous jumps. It is not surprising that the Brownian bridge reset search process is the less efficient of the two, as it will never locate the target on its way back to the origin since it is going through territory it has already explored. From (1.7) and (1.13) one sees that the optimal expected time to locate the target is about 6 percent longer for the Poissonian instantaneous reset search process than for the periodic instantaneous reset search process. We note that in the context of a search for a *deterministic* target, it was shown in [21] that the optimal expected time to locate the target for the periodic instantaneous reset search process is always less than for the Poissonian instantaneous search process (and also less than for a generalization of the Poissonian search process where the jump rate is time dependent). We see here that this advantage of the periodic case over the Poissonian case continues to hold for a centered Gaussian target distribution. As will be seen, the relative efficiencies of the three processes in the three dimensional case are quite different from the one-dimensional case, and in particular, the above-noted phenomenon no longer holds.

The expected value of the time interval between resets in the Poissonian instantaneous reset search process is  $\frac{1}{r}$ . Thus, for the optimal value of  $r$  in (1.7), the expected value of the time interval between resets is about  $2.04 \frac{\sigma^2}{D}$ . From (1.7) and (1.13), one sees that the optimal value of  $T$  for the Brownian bridge reset search process is about 3.6 times as large as that for the periodic instantaneous reset search process

We now turn to the corresponding results in three dimensions. As will be seen in (2.3), (3.10) and (4.5), the expected hitting time  $\tau_a$  of a point  $a \in \mathbb{R}^3$  with  $|a| > \epsilon_0$  depends on  $\epsilon_0$ , and diverges on the order  $\frac{1}{\epsilon_0}$  as  $\epsilon_0 \rightarrow 0$ , for all three of the search processes. Thus, in the case  $d = 3$ , it is appropriate to multiply each of the expressions in (1.4) by  $\epsilon_0$  and then consider the limit as  $\epsilon_0 \rightarrow 0$ . Here is the result for the Poissonian instantaneous reset search process.

**Theorem 4.**

$$(1.14) \quad \lim_{\epsilon_0 \rightarrow 0} \epsilon_0 \int_{\mathbb{R}^3} (E_0^{(3;r)} \tau_a) \mu_{\sigma^2}^{Gauss,3}(da) = \frac{2\sigma}{\sqrt{2\pi} r} \int_0^\infty x^3 e^{\sqrt{\frac{r}{D}} \sigma x} e^{-\frac{x^2}{2}} dx.$$

Equivalently, writing  $r = \frac{D}{\sigma^2} s$ , with  $s > 0$ ,

$$(1.15) \quad \lim_{\epsilon_0 \rightarrow 0} \epsilon_0 \int_{\mathbb{R}^3} (E_0^{(3;r)} \tau_a) \mu_{\sigma^2}^{Gauss,3}(da) = \frac{\sigma^3}{D} \left( \frac{2}{\sqrt{2\pi} s} \int_0^\infty x^3 e^{\sqrt{s} x} e^{-\frac{x^2}{2}} dx \right).$$

One has

$$(1.16) \quad \inf_{r>0} \lim_{\epsilon_0 \rightarrow 0} \epsilon_0 \int_{\mathbb{R}^3} (E_0^{(3;r)} \tau_a) \mu_{\sigma^2}^{Gauss,3}(da) \approx 13.09 \frac{\sigma^3}{D},$$

*with the infimum attained at  $r \approx 0.738 \frac{D}{\sigma^2}$ .*

Here is the corresponding result for the Brownian bridge reset search process.

**Theorem 5.**

$$(1.17) \quad \lim_{\epsilon_0 \rightarrow 0} \epsilon_0 \int_{\mathbb{R}^3} (E_0^{bb,3;T} \tau_a) \mu_{\sigma^2}^{Gauss,3}(da) = \begin{cases} \frac{2T^3 D^2 \sigma}{\sqrt{2\pi}(DT-4\sigma^2)^2}, & T > \frac{4\sigma^2}{D}; \\ \infty, & T \leq \frac{4\sigma^2}{D}. \end{cases}$$

*Equivalently, writing  $T = \frac{\sigma^2}{D} \mathcal{T}$ ,*

$$(1.18) \quad \lim_{\epsilon_0 \rightarrow 0} \epsilon_0 \int_{\mathbb{R}^3} (E_0^{bb,3;T} \tau_a) \mu_{\sigma^2}^{Gauss,3}(da) = \begin{cases} \frac{\sigma^3}{D} \left( \frac{2\mathcal{T}^3}{\sqrt{2\pi}(\mathcal{T}-4)^2} \right), & \mathcal{T} > 4; \\ \infty, & \mathcal{T} \leq 4. \end{cases}$$

One has

$$(1.19) \quad \inf_{T>0} \lim_{\epsilon_0 \rightarrow 0} \epsilon_0 \int_{\mathbb{R}^3} (E_0^{bb,3;T} \tau_a) \mu_{\sigma^2}^{Gauss,3}(da) \approx 21.54 \frac{\sigma^3}{D},$$

*with the infimum attained at  $T = 12.00 \frac{\sigma^2}{D}$ .*

And here is the corresponding result for the periodic instantaneous reset search process.

**Theorem 6.**

$$(1.20) \quad \lim_{\epsilon_0 \rightarrow 0} \epsilon_0 \int_{\mathbb{R}^3} (E_0^{(3;T)} \tau_a) \mu_{\sigma^2}^{Gauss,3}(da) = \begin{cases} 2\sqrt{DT} \int_0^\infty \frac{1}{\int_0^T \frac{1}{t^{\frac{3}{2}}} e^{-\frac{\sigma^2 x^2}{2Dt}} dt} x^2 e^{-\frac{x^2}{2}} dx, & T > \frac{\sigma^2}{D}, \\ \infty, & T \leq \frac{\sigma^2}{D}. \end{cases}$$

*Equivalently, writing  $T = \frac{\sigma^2}{D} \mathcal{T}$ , with  $\mathcal{T} > 0$ ,*

$$(1.21) \quad \lim_{\epsilon_0 \rightarrow 0} \epsilon_0 \int_{\mathbb{R}^3} (E_0^{(3;T)} \tau_a) \mu_{\sigma^2}^{Gauss,3}(da) = \begin{cases} \frac{\sigma^3}{D} \left( 2\mathcal{T} \int_0^\infty \frac{1}{\int_0^\mathcal{T} \frac{1}{s^{\frac{3}{2}}} e^{-\frac{x^2}{2s}} ds} x^2 e^{-\frac{x^2}{2}} dx \right), & \mathcal{T} > 1, \\ \infty, & \mathcal{T} \leq 1. \end{cases}$$

One has

$$(1.22) \quad \inf_{T>0} \lim_{\epsilon_0 \rightarrow 0} \epsilon_0 \int_{\mathbb{R}^3} (E_0^{(3;T)} \tau_a) \mu_{\sigma^2}^{Gauss,3}(da) \approx 22.775 \frac{\sigma^3}{D},$$

*with the infimum attained at  $T \approx 4.13 \frac{\sigma^2}{D}$ .*

**Conclusion for the three-dimensional case.** From Theorems 4–6, it follows that, as in the one-dimensional case, the appropriate scaling unit for the resetting rate  $r$  in the case of the Poissonian instantaneous reset search process is  $\frac{D}{\sigma^2}$ , and the appropriate scaling unit for the time interval  $T$  in the case of the Brownian bridge reset search process and the periodic reset search process is  $\frac{\sigma^2}{D}$ . *However, for all of these processes, the corresponding expected time to locate the target is an appropriate constant times  $\frac{\sigma^3}{D}$ , as opposed to  $\frac{\sigma^2}{D}$  in the one-dimensional case.* This seems to us to be an anomalous and surprising scaling.

Comparing the two time-inhomogeneous processes, one with instantaneous jump resetting and one with continuous resetting via the Brownian bridge, one sees from (1.19) and (1.22) that the optimal expected time to locate the target is about 6 percent longer for the one with instantaneous jumps than for the continuous one, which is completely different than in the one-dimensional case. Perhaps the explanation for this is that, unlike in the one-dimensional case, in the three-dimensional case the Brownian bridge reset search process can explore new territory on its way back to the origin. From (1.16), (1.19) and (1.22), one sees that the Poissonian instantaneous reset search process is by far the most efficient one of the three. The expected time to locate the target is about 65 percent and 74 percent longer for the other two processes. Note that the periodic instantaneous reset search process fares the worst in three dimensions while faring the best in one dimension.

In light of the anomalous scaling in three dimensions, it is natural to wonder what occurs in two dimensions. As noted above, we are able to handle the two-dimensional Poissonian instantaneous reset search process. Theorem 7 below shows that the scaling in this case is the natural  $\frac{\sigma^2}{D}$  scaling. As will be seen in the proof of Theorem 7 in section 7,  $E_0^{(2;T)}\tau_a$ , with  $|a| > \epsilon_0$ , depends on  $\epsilon_0$ , and diverges on the order  $|\log \epsilon_0|$  as  $\epsilon_0 \rightarrow 0$ . Thus, in the case  $d = 2$ , we multiply the first expression in (1.4) by  $\frac{1}{|\log \epsilon_0|}$  and then consider the limit as  $\epsilon_0 \rightarrow 0$ .

**Theorem 7.**

(1.23)

$$\lim_{\epsilon \rightarrow 0} \frac{1}{|\log \epsilon_0|} \int_{\mathbb{R}^2} (E_0^{(2;T)}\tau_a)\mu_{\sigma^2}^{Gauss,2}(da) = \frac{1}{r} \int_0^\infty \frac{1}{K_0(\sqrt{\frac{r}{D}}\sigma x)} x e^{-\frac{x^2}{2}} dx,$$

where  $K_0$  is the modified Bessel function of the second kind of order zero. Equivalently, writing  $r = \frac{D}{\sigma^2}s$ ,

(1.24)

$$\lim_{\epsilon \rightarrow 0} \frac{1}{|\log \epsilon_0|} \int_{\mathbb{R}^2} (E_0^{(2;T)}\tau_a)\mu_{\sigma^2}^{Gauss,2}(da) = \frac{\sigma^2}{D} \left( \frac{1}{s} \int_0^\infty \frac{1}{K_0(\sqrt{s}x)} x e^{-\frac{x^2}{2}} dx \right).$$

One has

$$(1.25) \quad \inf_{r>0} \lim_{\epsilon \rightarrow 0} \frac{1}{|\log \epsilon_0|} \int_{\mathbb{R}^2} (E_0^{(2;T)} \tau_a) \mu_{\sigma^2}^{Gauss,2}(da) \approx 4.77 \frac{\sigma^2}{D},$$

with the infimum attained at  $r \approx 0.713 \frac{D}{\sigma^2}$ .

**Remark.** Comparing (1.7) and (1.25), one sees that for the Poissonian instantaneous reset search process, the expected time to locate the target is about 34 percent longer in the two-dimensional case than in the one-dimensional case. Of course, there is no sense in making a comparison with the three-dimensional case since the scaling there is different.

As already mentioned, the expectation of  $\tau_a$  for fixed  $a$ , for all of the various cases is treated in sections 2–4. These results are then used to prove Theorems 1–7. The proofs of Theorems 1–3 are given in section 5, the proofs of Theorems 4–6 are given in section 6 and the proof of Theorem 7 is given in section 7.

## 2. CALCULATING THE EXPECTED VALUE OF $\tau_a$ FOR FIXED $a$ IN THE POISSONIAN INSTANTANEOUS RESET CASE

For the Poissonian instantaneous reset case, the calculation we need appears in the literature. In dimension  $d = 1$ ,

$$(2.1) \quad E_0^{(1;r)} \tau_a = \frac{1}{r} (e^{\sqrt{\frac{2r}{D}} |a|} - 1), \quad a \in \mathbb{R},$$

and in dimensions  $d \geq 2$ ,

$$(2.2) \quad E_0^{(d;r)} \tau_a = \frac{1}{r} \left( \left( \frac{\epsilon_0}{|a|} \right)^{1-\frac{d}{2}} \frac{K_{1-\frac{d}{2}}(\sqrt{\frac{r}{D}} \epsilon_0)}{K_{1-\frac{d}{2}}(\sqrt{\frac{r}{D}} |a|)} - 1 \right), \quad |a| > \epsilon_0,$$

where  $K_\nu$  denotes the modified Bessel function of the second kind of order  $\nu$  [9, 11]. Moreover, it is known that

$$K_{-\frac{1}{2}}(y) = \left( \frac{\pi}{2y} \right)^{\frac{1}{2}} e^{-y}.$$

Thus, from (2.2) we have

$$(2.3) \quad E_0^{(3;r)} \tau_a = \frac{1}{r} \left( \frac{|a|}{\epsilon_0} e^{\sqrt{\frac{r}{D}} (|a| - \epsilon_0)} - 1 \right), \quad |a| > \epsilon_0.$$

## 3. CALCULATING THE EXPECTED VALUE OF $\tau_a$ FOR FIXED $a$ IN THE BROWNIAN BRIDGE RESET CASE

We consider the Brownian bridge reset search process for dimensions  $d = 1$  and  $d = 3$ . For the one-dimensional case, we have the following result.

**Proposition 1.**

$$\begin{aligned}
(3.1) \quad E_0^{bb,1;T} \tau_a &= T(e^{\frac{2a^2}{DT}} - 1) + |a|e^{\frac{2a^2}{DT}} \int_0^T \frac{e^{-\frac{a^2}{2Dt(1-\frac{t}{T})}}}{\sqrt{2\pi Dt(1-\frac{t}{T})}} dt = \\
&T(e^{\frac{2a^2}{DT}} - 1) + \frac{2|a|e^{\frac{2a^2}{DT}}}{D} \int_a^\infty e^{-\frac{2x^2}{TD}} dx, \quad a \in \mathbb{R}.
\end{aligned}$$

*Proof.* By symmetry, it suffices to consider  $a > 0$ . Let  $W(\cdot)$  be a Brownian motion with diffusion coefficient  $D$  starting from the origin (the generator of the process is  $\frac{D}{2} \frac{d^2}{dx^2}$ ), and denote probabilities and expectations for this process by  $P_0$  and  $E_0$ . It is well-known [16, 2] that  $\tau_a$ , the hitting time of  $a \in \mathbb{R}$ , satisfies

$$P_0(\tau_a < T | W(T) = 0) = e^{-\frac{2a^2}{DT}}.$$

It follows from the definition of the Brownian bridge and the definition of  $X^{bb,1;T}(\cdot)$  that the above equation is equivalent to

$$(3.2) \quad P_0^{bb,1;T}(\tau_a < T) = e^{-\frac{2a^2}{DT}}.$$

It is very well-known from the reflection principle [16, 25] that the hitting time  $\tau_a$  for  $W(\cdot)$  has a density  $f(t)$  given by

$$(3.3) \quad f(t) = \frac{1}{\sqrt{2\pi D}} \frac{a}{t^{\frac{3}{2}}} e^{-\frac{a^2}{2Dt}}, \quad t > 0.$$

Of course, the density of  $W(t)$  is  $\frac{e^{-\frac{a^2}{2Dt}}}{\sqrt{2\pi Dt}}$ ,  $a \in \mathbb{R}$ . Thus,  $\tau_a$ , the hitting time for  $W(t)$ ,  $0 \leq t \leq T$ , conditioned on  $W(T) = 0$ , or equivalently, the hitting time under  $P_0^{bb,1;T}$ , has sub-density

$$(3.4) \quad \frac{f(t) \frac{1}{\sqrt{2\pi D(T-t)}} e^{-\frac{a^2}{2D(T-t)}}}{\frac{1}{\sqrt{2\pi DT}}} = \frac{ae^{-\frac{a^2}{2Dt(1-\frac{t}{T})}}}{\sqrt{2\pi D(1-\frac{t}{T})} t^{\frac{3}{2}}}, \quad 0 < t < T.$$

Consequently, from the definition of  $X^{bb,1;T}(\cdot)$ ,

$$(3.5) \quad E_0^{bb,1;T}(\tau_a 1_{\tau_a < T}) = E_0(\tau_a 1_{\tau_a < T} | W(T) = 0) = a \int_0^T \frac{e^{-\frac{a^2}{2Dt(1-\frac{t}{T})}}}{\sqrt{2\pi Dt(1-\frac{t}{T})}} dt.$$

From (3.2) and the definition of  $X^{bb,1;T}(\cdot)$ , it follows that

$$(3.6) \quad P_0^{bb,1;T}(\tau_a \in (nT, (n+1)T]) = (1 - e^{-\frac{2a^2}{DT}})^n e^{-\frac{2a^2}{DT}}.$$

Also, from (3.2), (3.5) and the definition of  $X^{\text{bb},1;T}(\cdot)$  it follows that

$$(3.7) \quad \begin{aligned} E_0^{\text{bb},1;T}(\tau_a | \tau_a \in (nT, (n+1)T]) &= nT + E_0^{\text{bb},1;T}(\tau_a | \tau_a < T) = \\ nT + \frac{E_0^{\text{bb},1;T}(\tau_a 1_{\tau_a < T})}{P_0^{\text{bb},1;T}(\tau_a < T)} &= nT + ae^{\frac{2a^2}{DT}} \int_0^T \frac{e^{-\frac{a^2}{2Dt(1-\frac{t}{T})}}}{\sqrt{2\pi Dt(1-\frac{t}{T})}} dt. \end{aligned}$$

Now (3.6) and (3.7) yield

$$\begin{aligned} E_0^{\text{bb},1;T} \tau_a &= \sum_{n=0}^{\infty} E_0^{\text{bb},1;T}(\tau_a | \tau_a \in (nT, (n+1)T]) P_0^{\text{bb},1;T}(\tau_a \in (nT, (n+1)T]) = \\ \sum_{n=0}^{\infty} \left( nT + ae^{\frac{2a^2}{DT}} \int_0^T \frac{e^{-\frac{a^2}{2Dt(1-\frac{t}{T})}}}{\sqrt{2\pi Dt(1-\frac{t}{T})}} dt \right) (1 - e^{-\frac{2a^2}{DT}})^n e^{-\frac{2a^2}{DT}} &= \\ T(e^{\frac{2a^2}{DT}} - 1) + ae^{\frac{2a^2}{DT}} \int_0^T \frac{e^{-\frac{a^2}{2Dt(1-\frac{t}{T})}}}{\sqrt{2\pi Dt(1-\frac{t}{T})}} dt, \end{aligned}$$

which gives the first equality in (3.1). For the second equality in (3.1), we need to prove that

$$(3.8) \quad \int_0^T \frac{e^{-\frac{a^2}{2Dt(1-\frac{t}{T})}}}{\sqrt{2\pi Dt(1-\frac{t}{T})}} dt = \frac{2}{D} \int_a^{\infty} e^{-\frac{2x^2}{TD}} dx.$$

Let  $G(a) = \int_0^T \frac{e^{-\frac{a^2}{2Dt(1-\frac{t}{T})}}}{\sqrt{2\pi Dt(1-\frac{t}{T})}} dt$ . Then  $G'(a) = -\frac{a}{D\sqrt{2\pi D}} \int_0^T \frac{e^{-\frac{a^2}{2Dt(1-\frac{t}{T})}}}{(t(1-\frac{t}{T}))^{\frac{3}{2}}} dt$ . The integral appearing in  $G'(a)$  is evaluated in (3.23) in the course of the proof of Theorem 2. This gives

$$(3.9) \quad G'(a) = -\frac{a}{D\sqrt{2\pi D}} \frac{2\sqrt{2\pi D}}{a} e^{-\frac{2a^2}{TD}} = -\frac{2}{D} e^{-\frac{2a^2}{TD}}.$$

Since  $\lim_{a \rightarrow \infty} G(a) = 0$ , we have

$$G(a) = -\int_a^{\infty} G'(x) dx = \frac{2}{D} \int_a^{\infty} e^{-\frac{2x^2}{TD}} dx,$$

proving (3.8). □

For the three-dimensional case, we have the following result, giving upper and lower bounds which depend on  $\epsilon_0$ .

**Proposition 2.**

(3.10)

$$E_0^{bb,3;T} \tau_a \leq T \left( \frac{|a| + \epsilon_0}{|a| - \epsilon_0} \frac{|a|}{2\epsilon_0} e^{\frac{2(|a| + \epsilon_0)^2}{DT}} - 1 \right) + T \frac{|a| + \epsilon_0}{2(|a| - \epsilon_0)} e^{\frac{8|a|\epsilon_0}{DT}}, \quad |a| > \epsilon_0;$$

$$E_0^{bb,3;T} \tau_a \geq T \left( \frac{|a|}{2\epsilon_0} e^{\frac{2(|a| - \epsilon_0)^2}{DT}} - 1 \right) + T \frac{|a| - \epsilon_0}{2(|a| + \epsilon_0)} e^{-\frac{8|a|\epsilon_0}{DT}}, \quad |a| > \epsilon_0.$$

*Also,*

$$(3.11) \quad \sup_{\epsilon_0, a: 0 < \epsilon_0 < |a| \leq 1} \epsilon_0 E_0^{bb,3;T} \tau_a < \infty.$$

**Remark.** We note that (3.11) is a technical result that will be needed because the right hand side of the first line in (3.10) is unbounded as  $|a| \rightarrow \epsilon_0$ .

*Proof.* Let  $W(t)$  be a three-dimensional Brownian motion with diffusion coefficient  $D$  and denote probabilities for the process starting from  $b \in \mathbb{R}^3$  by  $P_b$ . Abusing notation, let  $P_0(\tau_a = t)$  denote the density of the distribution of  $\tau_a$  under  $P_0$ ; we will make similar abuses of notation for other densities in the sequel. Of course by isotropy,  $P_0(\tau_a = t) = P_a(\tau_0 = t)$ , and this latter density can be found in [15] in the case that the diffusion coefficient  $D$  is equal to one. After appropriate scaling to take into account  $D$ , this gives

$$(3.12) \quad P_0(\tau_a = t) = \frac{\epsilon_0}{|a|} \frac{|a| - \epsilon_0}{\sqrt{2\pi D} t^{\frac{3}{2}}} e^{-\frac{(|a| - \epsilon_0)^2}{2Dt}}, \quad |a| > \epsilon_0.$$

In the sequel, in all formulas involving  $a$  and  $\epsilon_0$ , it will be tacitly assumed that  $|a| > \epsilon_0$ . From (3.12), the strong Markov property and the definition of  $X^{bb,3,T}(\cdot)$ , we have

$$(3.13) \quad P_0^{bb,3;T}(\tau_a = t) = \frac{P_0(\tau_a = t) \int_{\nu \in \mathbb{R}^3: |\nu|=1} P_{a+\epsilon_0\nu}(W(T-t) = 0) \mu_{a,t}(d\nu)}{P_0(W(T) = 0)},$$

where  $\mu_{a,t}$  is the distribution under  $P_0$  of  $W(\tau_a)$ , conditioned on  $\{\tau_a = t\}$ . Of course,

$$(3.14) \quad P_b(W(t) = a) = \frac{e^{-\frac{|b-a|^2}{2Dt}}}{(2\pi Dt)^{\frac{3}{2}}}, \quad a, b \in \mathbb{R}^3.$$

Thus,  $P_{a+\epsilon_0\nu}(W(T-t) = 0)$  attains its maximum and minimum over  $\{\nu \in \mathbb{R}^3 : |\nu| = 1\}$  at  $\nu = -\frac{a}{|a|}$  and  $\nu = \frac{a}{|a|}$  respectively, giving

$$(3.15) \quad \frac{e^{-\frac{(|a| + \epsilon_0)^2}{2D(T-t)}}}{(2\pi D(T-t))^{\frac{3}{2}}} \leq P_{a+\epsilon_0\nu}(W(T-t) = 0) \leq \frac{e^{-\frac{(|a| - \epsilon_0)^2}{2D(T-t)}}}{(2\pi D(T-t))^{\frac{3}{2}}}, \quad |\nu| = 1.$$

From (3.12)-(3.15), we conclude that

$$(3.16) \quad \frac{\epsilon_0}{|a|} \frac{|a| - \epsilon_0}{\sqrt{2\pi D}} \frac{e^{-\frac{(|a|+\epsilon_0)^2}{2D(T-t)}} e^{-\frac{(|a|-\epsilon_0)^2}{2Dt}}}{(t(1-\frac{t}{T}))^{\frac{3}{2}}} \leq P_0^{\text{bb},3;T}(\tau_a = t) \leq \frac{\epsilon_0}{|a|} \frac{|a| - \epsilon_0}{\sqrt{2\pi D}} \frac{e^{-\frac{(|a|-\epsilon_0)^2}{2Dt(1-\frac{t}{T})}}}{(t(1-\frac{t}{T}))^{\frac{3}{2}}}.$$

We will use the lower bound in (3.16) to prove (3.11), however for the proof of the lower bound in (3.10), we will use the following lower bound, which is obtained by replacing the term  $|a| - \epsilon$  in the exponent on the left hand side of (3.16) by  $|a| + \epsilon$ :

$$(3.17) \quad \frac{\epsilon_0}{|a|} \frac{|a| - \epsilon_0}{\sqrt{2\pi D}} \frac{e^{-\frac{(|a|+\epsilon_0)^2}{2Dt(1-\frac{t}{T})}}}{(t(1-\frac{t}{T}))^{\frac{3}{2}}} \leq P_0^{\text{bb},3;T}(\tau_a = t).$$

From (3.2) and (3.4), it follows that

$$(3.18) \quad \frac{1}{\sqrt{2\pi D}} \int_0^T b \frac{e^{-\frac{b^2}{2Dt(1-\frac{t}{T})}}}{(1-\frac{t}{T})^{\frac{1}{2}} t^{\frac{3}{2}}} dt = e^{-\frac{2b^2}{TD}}, \quad b > 0.$$

Making the change of variables  $s = T - t$  gives

$$(3.19) \quad \int_0^T \frac{e^{-\frac{b^2}{2Dt(1-\frac{t}{T})}}}{(1-\frac{t}{T})^{\frac{1}{2}} t^{\frac{3}{2}}} dt = \int_0^T \frac{e^{-\frac{b^2}{2D(T-s)\frac{s}{T}}}}{(\frac{s}{T})^{\frac{1}{2}} (T-s)^{\frac{3}{2}}} ds = \frac{1}{T} \int_0^T \frac{e^{-\frac{b^2}{2Ds(1-\frac{s}{T})}}}{s^{\frac{1}{2}} (1-\frac{s}{T})^{\frac{3}{2}}} ds.$$

From (3.18) and (3.19), we have

$$(3.20) \quad \frac{1}{\sqrt{2\pi D}} \int_0^T b \frac{e^{-\frac{b^2}{2Dt(1-\frac{t}{T})}}}{t^{\frac{1}{2}} (1-\frac{t}{T})^{\frac{3}{2}}} dt = T e^{-\frac{2b^2}{TD}}.$$

Now (3.16) and (3.20) give

$$(3.21) \quad \begin{aligned} E_0^{\text{bb},3;T} \tau_a 1_{\tau_a \leq T} &\leq \frac{\epsilon_0}{|a|} \frac{|a| - \epsilon_0}{\sqrt{2\pi D}} \int_0^T \frac{e^{-\frac{(|a|-\epsilon_0)^2}{2Dt(1-\frac{t}{T})}}}{t^{\frac{1}{2}} (1-\frac{t}{T})^{\frac{3}{2}}} dt = \frac{\epsilon_0}{|a|} T e^{-\frac{2(|a|-\epsilon_0)^2}{TD}}; \\ E_0^{\text{bb},3;T} \tau_a 1_{\tau_a \leq T} &\geq \frac{\epsilon_0}{|a|} \frac{|a| - \epsilon_0}{\sqrt{2\pi D}} \int_0^T \frac{e^{-\frac{(|a|+\epsilon_0)^2}{2Dt(1-\frac{t}{T})}}}{t^{\frac{1}{2}} (1-\frac{t}{T})^{\frac{3}{2}}} dt = \frac{\epsilon_0}{|a|} \frac{|a| - \epsilon_0}{|a| + \epsilon_0} T e^{-\frac{2(|a|+\epsilon_0)^2}{TD}}. \end{aligned}$$

From (3.16) and (3.17), we have

$$(3.22) \quad \frac{\epsilon_0}{|a|} \frac{|a| - \epsilon_0}{\sqrt{2\pi D}} \int_0^T \frac{e^{-\frac{(|a|+\epsilon_0)^2}{2Dt(1-\frac{t}{T})}}}{(t(1-\frac{t}{T}))^{\frac{3}{2}}} dt \leq P_0^{\text{bb},3;T}(\tau_a \leq T) \leq \frac{\epsilon_0}{|a|} \frac{|a| - \epsilon_0}{\sqrt{2\pi D}} \int_0^T \frac{e^{-\frac{(|a|-\epsilon_0)^2}{2Dt(1-\frac{t}{T})}}}{(t(1-\frac{t}{T}))^{\frac{3}{2}}} dt.$$



We now show that

$$(3.23) \quad \int_0^T \frac{e^{-\frac{b^2}{2Dt(1-\frac{t}{T})}}}{(t(1-\frac{t}{T}))^{\frac{3}{2}}} dt = \frac{2\sqrt{2\pi D}}{b} e^{-\frac{2b^2}{TD}}, \quad b > 0.$$

Indeed, (3.23) follows from the following calculation, in which we use (3.18) for the first equality and (3.20) for the last inequality.

$$\begin{aligned} \frac{\sqrt{2\pi D}}{b} e^{-\frac{2b^2}{TD}} &= \int_0^T \frac{e^{-\frac{b^2}{2Dt(1-\frac{t}{T})}}}{(1-\frac{t}{T})^{\frac{1}{2}} t^{\frac{3}{2}}} dt = \int_0^T \frac{e^{-\frac{b^2}{2Dt(1-\frac{t}{T})}}}{(t(1-\frac{t}{T}))^{\frac{3}{2}}} (1-\frac{t}{T}) dt = \\ &= \int_0^T \frac{e^{-\frac{b^2}{2Dt(1-\frac{t}{T})}}}{(t(1-\frac{t}{T}))^{\frac{3}{2}}} dt - \frac{1}{T} \int_0^T \frac{e^{-\frac{b^2}{2Dt(1-\frac{t}{T})}}}{t^{\frac{1}{2}} (1-\frac{t}{T})^{\frac{3}{2}}} dt = \int_0^T \frac{e^{-\frac{b^2}{2Dt(1-\frac{t}{T})}}}{(t(1-\frac{t}{T}))^{\frac{3}{2}}} dt - \frac{\sqrt{2\pi D}}{b} e^{-\frac{2b^2}{TD}}. \end{aligned}$$

From (3.22) and (3.23), we have

$$(3.24) \quad \frac{2\epsilon_0 |a| - \epsilon_0}{|a| |a| + \epsilon_0} e^{-\frac{2(|a|+\epsilon_0)^2}{TD}} \leq P_0^{\text{bb},3;T}(\tau_a \leq T) \leq \frac{2\epsilon_0}{|a|} e^{-\frac{2(|a|-\epsilon_0)^2}{TD}}.$$

We now write

$$(3.25) \quad E_0^{\text{bb},3;T} \tau_a = \sum_{n=0}^{\infty} E_0^{\text{bb},3;T}(\tau_a | \tau_a \in (nT, (n+1)T]) P_0^{\text{bb},3;T}(\tau_a \in (nT, (n+1)T]).$$

From the definition of  $X^{\text{bb},3;T}$ , we have

$$(3.26) \quad E_0^{\text{bb},3;T}(\tau_a | \tau_a \in (nT, (n+1)T]) = nT + E_0^{\text{bb},3;T}(\tau_a | \tau_a \leq T) = nT + \frac{E_0^{\text{bb},3;T} \tau_a 1_{\tau_a \leq T}}{P_0^{\text{bb},3;T}(\tau_a \leq T)}$$

and

$$(3.27) \quad P_0^{\text{bb},3;T}(\tau_a \in (nT, (n+1)T]) = (P_0^{\text{bb},3;T}(\tau_a > T))^n P_0^{\text{bb},3;T}(\tau_a \leq T).$$

Since for  $q \in (0, 1)$ , one has  $\sum_{n=0}^{\infty} n(1-q)^n q = \frac{1-q}{q}$ , which is decreasing in  $q$ , we have from (3.24)

$$(3.28) \quad \begin{aligned} \sum_{n=0}^{\infty} n (P_0^{\text{bb},3;T}(\tau_a > T))^n P_0^{\text{bb},3;T}(\tau \leq T) &\leq \frac{|a|(|a| + \epsilon_0)}{2\epsilon_0(|a| - \epsilon_0)} e^{\frac{2(|a|+\epsilon_0)^2}{TD}} - 1; \\ \sum_{n=0}^{\infty} n (P_0^{\text{bb},3;T}(\tau_a > T))^n P_0^{\text{bb},3;T}(\tau \leq T) &\geq \frac{|a|}{2\epsilon_0} e^{\frac{2(|a|-\epsilon_0)^2}{TD}} - 1. \end{aligned}$$

Now (3.10) follows from (3.25)-(3.28) along with (3.24) and (3.21).

We now prove (3.11). From the upper bound in (3.10), it suffices to consider the case that  $|a| - \epsilon_0$  is small; indeed,  $|a| - \epsilon_0$  being small is the

only thing that can possibly prevent the left hand side of (3.11) from being finite. Thus we can and will assume that

$$(3.29) \quad (|a| - \epsilon_0)^2 \leq \frac{T}{4}.$$

(Of course, since from (3.11) we are always assuming that  $|a| \leq 1$ , the assumption (3.29) holds automatically if  $T \geq 4$ .) Let

$$p(a) = P_0^{\text{bb},3;T}(\tau_a \leq T).$$

From the definition of the Brownian bridge reset search process,

$$P_0^{\text{bb},3;T}((M-1)T \leq \tau_a \leq MT) = (1 - p(a))^{M-1}p(a), \quad M \in \mathbb{N}.$$

Thus,

$$(3.30) \quad \begin{aligned} E_0^{\text{bb},3;T} \tau_a &\leq \sum_{M=1}^{\infty} MT P_0^{\text{bb},3;T}((M-1)T \leq \tau_a \leq MT) = \\ T p(a) \sum_{M=1}^{\infty} M (1 - p(a))^{M-1} &= \frac{T}{p(a)}. \end{aligned}$$

We now obtain a lower bound on  $p(a)$ . Using the lower bound in (3.16) for the second inequality below, we have

(3.31)

$$p(a) = P_0^{\text{bb},3;T}(\tau_a \leq T) > P_0^{\text{bb},3;T}(|a - \epsilon_0|^2 \leq \tau_a \leq \frac{T}{2}) \geq$$

$$\int_{|a-\epsilon_0|^2}^{\frac{T}{2}} \frac{\epsilon_0}{|a|} \frac{|a| - \epsilon_0}{\sqrt{2\pi D}} e^{-\frac{(|a|+\epsilon_0)^2}{2D(T-t)}} e^{-\frac{(|a|-\epsilon_0)^2}{2Dt}} \frac{1}{(t(1-\frac{t}{T}))^{\frac{3}{2}}} dt \geq$$

$$C\epsilon_0 \int_{(|a|-\epsilon_0)^2}^{\frac{T}{2}} \frac{|a| - \epsilon_0}{t^{\frac{3}{2}}} dt = 2C\epsilon_0 \left(1 - \frac{\sqrt{2}(|a| - \epsilon_0)}{\sqrt{T}}\right) \geq 2C\epsilon_0 \left(1 - \frac{\sqrt{2}}{2}\right),$$

for  $|a| \leq 1$  and  $a$  and  $\epsilon_0$  satisfying (3.29), where  $C$  depends only on  $T$  and  $D$ .

From (3.30) and (3.31), we conclude that  $E_0^{\text{bb},3;T} \tau_a \leq \frac{T}{2C\epsilon_0(1-\frac{\sqrt{2}}{2})}$ , for  $a$  and  $\epsilon_0$  as in (3.31). This completes the proof of (3.11).  $\square$

#### 4. CALCULATING THE EXPECTED VALUE OF $\tau_a$ FOR FIXED $a$ IN THE PERIODIC INSTANTANEOUS RESET CASE

We consider the periodic instantaneous reset process for dimensions  $d = 1$  and  $d = 3$ . The formulas in this section (sometimes in slightly different forms) appear, for example, in [4] (for one and three dimensions), [3] (for one dimension) and [14] (for all dimensions). For completeness, we supply the short proofs. In the one-dimensional case, we have the following result.

**Proposition 3.**

$$(4.1) \quad E_0^{1;T} \tau_a = T \left( \left( \int_0^T \frac{|a|}{\sqrt{2\pi D}} \frac{1}{t^{\frac{3}{2}}} e^{-\frac{a^2}{2Dt}} dt \right)^{-1} - 1 \right) + \frac{\int_0^T \frac{1}{t^{\frac{1}{2}}} e^{-\frac{a^2}{2Dt}} dt}{\int_0^T \frac{1}{t^{\frac{3}{2}}} e^{-\frac{a^2}{2Dt}} dt}, \quad a \neq 0.$$

*Proof.* By symmetry, it suffices to consider  $a > 0$ . From the definition of the process  $X^{1;T}$ , the probability of the event  $\{\tau_a < T\}$  is the same as it is for a Brownian motion with diffusion coefficient  $D$ . Thus, from (3.3), we have

$$(4.2) \quad P_0^{1;T}(\tau_a < T) = \int_0^T \frac{a}{\sqrt{2\pi D}} \frac{1}{t^{\frac{3}{2}}} e^{-\frac{a^2}{2Dt}} dt.$$

From (4.2) and the definition of  $X^{1;T}$ , we have

$$(4.3) \quad P_0^{1;T}(\tau_a \in (nT, (n+1)T]) = \left(1 - \int_0^T \frac{a}{\sqrt{2\pi D}} \frac{1}{t^{\frac{3}{2}}} e^{-\frac{a^2}{2Dt}} dt\right)^n \int_0^T \frac{a}{\sqrt{2\pi D}} \frac{1}{t^{\frac{3}{2}}} e^{-\frac{a^2}{2Dt}} dt,$$

and

$$(4.4) \quad E_0^{1;T}(\tau_a | \tau_a \in (nT, (n+1)T]) = nT + \frac{\int_0^T \frac{1}{t^{\frac{1}{2}}} e^{-\frac{a^2}{2Dt}} dt}{\int_0^T \frac{1}{t^{\frac{3}{2}}} e^{-\frac{a^2}{2Dt}} dt}.$$

Writing

$$E_0^{1;T} \tau_a = \sum_{n=0}^{\infty} E_0^{1;T}(\tau_a | \tau_a \in (nT, (n+1)T]) P_0^{1;T}(\tau_a \in (nT, (n+1)T]),$$

the theorem follows from (4.3) and (4.4).  $\square$

In the three-dimensional case, we have the following result.

**Proposition 4.**

(4.5)

$$E_0^{3;T} \tau_a = T \left( \left( \int_0^T \frac{\epsilon_0(|a| - \epsilon_0)}{|a|\sqrt{2\pi D}} \frac{1}{t^{\frac{3}{2}}} e^{-\frac{(|a| - \epsilon_0)^2}{2Dt}} dt \right)^{-1} - 1 \right) + \frac{\int_0^T \frac{1}{t^{\frac{1}{2}}} e^{-\frac{(|a| - \epsilon_0)^2}{2Dt}} dt}{\int_0^T \frac{1}{t^{\frac{3}{2}}} e^{-\frac{(|a| - \epsilon_0)^2}{2Dt}} dt}, \quad |a| > \epsilon_0.$$

*Proof.* From the definition of the process  $X^{3;T}$ , the probability of the event  $\{\tau_a < T\}$  is the same as it is for a three-dimensional Brownian motion with diffusion coefficient  $D$ . Thus, from (3.12), we have

$$(4.6) \quad P_0^{1;T}(\tau_a < T) = \int_0^T \frac{\epsilon_0(|a| - \epsilon_0)}{|a|\sqrt{2\pi D}} \frac{1}{t^{\frac{3}{2}}} e^{-\frac{(|a| - \epsilon_0)^2}{2Dt}} dt.$$

The proof of the proposition now follows exactly as the proof of Proposition 3, but with (4.6) replacing (4.2).  $\square$

## 5. PROOFS OF THEOREMS 1-3

*Proof of Theorem 1.* From (2.1), we have

$$(5.1) \quad \int_{\mathbb{R}} (E_0^{(1;r)} \tau_a) \mu_{\sigma^2}^{\text{Gauss},1}(da) = 2 \int_0^\infty \frac{e^{\sqrt{\frac{2r}{D}}a} - 1}{r} \frac{e^{-\frac{a^2}{2\sigma^2}}}{\sqrt{2\pi}\sigma} da.$$

Also,

$$(5.2) \quad \int_0^\infty \frac{e^{\sqrt{\frac{2r}{D}}a} e^{-\frac{a^2}{2\sigma^2}}}{\sqrt{2\pi}\sigma} da = e^{\frac{r\sigma^2}{D}} \int_0^\infty \frac{e^{-\frac{(a-\sqrt{\frac{2r}{D}}\sigma^2)^2}{2\sigma^2}}}{\sqrt{2\pi}\sigma} da = e^{\frac{r\sigma^2}{D}} \int_{-\sqrt{\frac{2r}{D}}\sigma}^\infty \frac{e^{-\frac{x^2}{2}}}{\sqrt{2\pi}} dx.$$

We obtain (1.5) from (5.1) and (5.2). A change of variables in (1.5) yields (1.6). Finally, (1.7) was obtained from (1.6) using the Desmos graphing calculator.  $\square$

*Proof of Theorem 2.* From (3.1), we have

$$(5.3) \quad \begin{aligned} \int_{\mathbb{R}} (E_0^{\text{bb},1;T} \tau_a) \mu_{\sigma^2}^{\text{Gauss},1}(da) &= 2T \int_0^\infty (e^{\frac{2a^2}{DT}} - 1) \frac{e^{-\frac{a^2}{2\sigma^2}}}{\sqrt{2\pi}\sigma} da + \\ &2 \int_0^\infty a e^{\frac{2a^2}{DT}} \left( \int_0^T \frac{e^{-\frac{a^2}{2Dt(1-\frac{t}{T})}}}{\sqrt{2\pi Dt(1-\frac{t}{T})}} dt \right) \frac{e^{-\frac{a^2}{2\sigma^2}}}{\sqrt{2\pi}\sigma} da. \end{aligned}$$

The first integral on the right hand side of (5.3) is infinite if  $T \leq \frac{4\sigma^2}{D}$ . From now on, we assume that  $T > \frac{4\sigma^2}{D}$ . We have

$$2 \int_0^\infty e^{\frac{2a^2}{DT}} e^{-\frac{a^2}{2\sigma^2}} da = 2 \int_0^\infty e^{-\frac{1}{2} \frac{DT-4\sigma^2}{DT\sigma^2} a^2} da = \sqrt{2\pi \frac{DT\sigma^2}{DT-4\sigma^2}}.$$

Thus, the first term on the right hand side of (5.3) satisfies

$$(5.4) \quad 2T \int_0^\infty (e^{\frac{2a^2}{DT}} - 1) \frac{e^{-\frac{a^2}{2\sigma^2}}}{\sqrt{2\pi}\sigma} da = T \left( \frac{DT}{DT-4\sigma^2} \right)^{\frac{1}{2}} - T.$$

We now turn to the second term on the right hand side of (5.3). We have

$$(5.5) \quad \begin{aligned} \int_0^\infty a e^{\frac{2a^2}{DT}} e^{-\frac{a^2}{2Dt(1-\frac{t}{T})}} e^{-\frac{a^2}{2\sigma^2}} da &= \int_0^\infty a e^{-\frac{1}{2} \frac{T^2\sigma^2+t(T-t)(DT-4\sigma^2)}{DtT(T-t)\sigma^2} a^2} da = \\ &\frac{DtT(T-t)\sigma^2}{T^2\sigma^2+t(T-t)(DT-4\sigma^2)}. \end{aligned}$$

Using (5.5), we can write the second term on the right hand side of (5.3) as  
(5.6)

$$\begin{aligned} & 2 \int_0^\infty a e^{\frac{2a^2}{DT}} \left( \int_0^T \frac{e^{-\frac{a^2}{2Dt(1-\frac{t}{T})}}}{\sqrt{2\pi Dt(1-\frac{t}{T})}} dt \right) \frac{e^{-\frac{a^2}{2\sigma^2}}}{\sqrt{2\pi}\sigma} da = \\ & \frac{T^{\frac{3}{2}}\sigma}{\pi} \int_0^T \frac{\sqrt{Dt(T-t)}}{T^2\sigma^2 + t(T-t)(DT-4\sigma^2)} dt = \frac{2T^{\frac{3}{2}}\sigma}{\pi} \int_0^{\frac{T}{2}} \frac{\sqrt{Dt(T-t)}}{T^2\sigma^2 + t(T-t)(DT-4\sigma^2)} dt. \end{aligned}$$

Make the substitution  $x = \sqrt{t(T-t)}$ . Then  $t = \frac{1}{2}(T - (T^2 - 4x^2)^{\frac{1}{2}})$  and  $dt = 2x(T^2 - 4x^2)^{-\frac{1}{2}} dx$ . We obtain

$$(5.7) \quad \int_0^{\frac{T}{2}} \frac{\sqrt{Dt(T-t)}}{T^2\sigma^2 + t(T-t)(DT-4\sigma^2)} dt = 2\sqrt{D} \int_0^{\frac{T}{2}} \frac{1}{(T^2 - 4x^2)^{\frac{1}{2}}} \left( \frac{x^2}{T^2\sigma^2 + x^2(DT-4\sigma^2)} \right) dx.$$

Now make the substitution  $x = \frac{T}{2} \sin \theta$ . Then  $dx = \frac{T}{2} \cos \theta d\theta$ . We obtain

$$(5.8) \quad \int_0^{\frac{T}{2}} \frac{1}{(T^2 - 4x^2)^{\frac{1}{2}}} \left( \frac{x^2}{T^2\sigma^2 + x^2(DT-4\sigma^2)} \right) dx = \frac{1}{8} \int_0^{\frac{\pi}{2}} \frac{\sin^2 \theta}{\sigma^2 + \frac{DT-4\sigma^2}{4} \sin^2 \theta} d\theta.$$

We write

$$\begin{aligned} & \frac{\sin^2 \theta}{\sigma^2 + \frac{DT-4\sigma^2}{4} \sin^2 \theta} = \frac{4}{DT-4\sigma^2} \frac{\sin^2 \theta}{\sin^2 \theta + \frac{4\sigma^2}{DT-4\sigma^2}} = \\ & \frac{4}{DT-4\sigma^2} - \frac{16\sigma^2}{(DT-4\sigma^2)^2} \frac{1}{\sin^2 \theta + \frac{4\sigma^2}{DT-4\sigma^2}}. \end{aligned}$$

Thus,

$$(5.9) \quad \int_0^{\frac{\pi}{2}} \frac{\sin^2 \theta}{\sigma^2 + \frac{DT-4\sigma^2}{4} \sin^2 \theta} d\theta = \frac{2\pi}{DT-4\sigma^2} - \frac{16\sigma^2}{(DT-4\sigma^2)^2} \int_0^{\frac{\pi}{2}} \frac{1}{\sin^2 \theta + \frac{4\sigma^2}{DT-4\sigma^2}} d\theta.$$

Making the substitution  $\tan \theta = s$ , in which case  $\sin \theta = \frac{s}{\sqrt{1+s^2}}$  and  $d\theta = \frac{1}{1+s^2} ds$ , we obtain for any  $A > 0$ ,

$$(5.10) \quad \int_0^{\frac{\pi}{2}} \frac{1}{\sin^2 \theta + A} d\theta = \int_0^\infty \frac{1}{A + (A+1)s^2} ds = \frac{1}{A+1} \sqrt{\frac{A+1}{A}} \arctan \sqrt{\frac{A+1}{A}} s \Big|_0^\infty = \frac{\pi}{2\sqrt{A(A+1)}}.$$

From (5.10), we have

$$(5.11) \quad \int_0^{\frac{\pi}{2}} \frac{1}{\sin^2 \theta + \frac{4\sigma^2}{DT-4\sigma^2}} d\theta = \frac{\pi}{2} \left( \frac{4\sigma^2}{DT-4\sigma^2} \left( \frac{4\sigma^2}{DT-4\sigma^2} + 1 \right) \right)^{-\frac{1}{2}} = \frac{\pi(DT-4\sigma^2)}{4\sigma\sqrt{DT}}.$$

From (5.6)-(5.9) and (5.11), we obtain  
(5.12)

$$\begin{aligned} & 2 \int_0^\infty a e^{\frac{2a^2}{DT}} \left( \int_0^T \frac{e^{-\frac{a^2}{2Dt(1-\frac{t}{T})}}}{\sqrt{2\pi Dt(1-\frac{t}{T})}} dt \right) \frac{e^{-\frac{a^2}{2\sigma^2}}}{\sqrt{2\pi\sigma}} da = \\ & \left( \frac{2T^{\frac{3}{2}}\sigma}{\pi} \right) (2\sqrt{D}) \left( \frac{1}{8} \right) \left( \frac{2\pi}{DT-4\sigma^2} - \frac{16\sigma^2}{(DT-4\sigma^2)^2} \frac{\pi(DT-4\sigma^2)}{4\sigma\sqrt{DT}} \right) = \\ & \frac{T^{\frac{3}{2}}\sigma\sqrt{D}}{2\pi} \frac{2\pi\sqrt{DT}-4\sigma\pi}{(DT-4\sigma^2)\sqrt{DT}} = \frac{T^{\frac{3}{2}}\sigma\sqrt{D}}{2\pi} \frac{2\pi(\sqrt{DT}-2\sigma)}{(DT-4\sigma^2)\sqrt{DT}} = \frac{T\sigma}{\sqrt{DT}+2\sigma}. \end{aligned}$$

Now (1.8) follows from (5.3), (5.4) and (5.12). A change of variables in (1.8) yields (1.9). Finally, (1.10) was obtained from (1.9) using the Desmos graphing calculator.  $\square$

*Proof of Theorem 3.* We begin by showing that the left hand side of (1.11) is in fact finite if and only if  $T > \frac{\sigma^2}{D}$ . We leave it to the reader to show that the second term on the right hand side of (4.1) is bounded as  $a \rightarrow \infty$ . (Make the change of variables,  $s = \frac{t}{a^2}$ , then let  $x = \frac{1}{a^2}$  and apply l'Hôpital's rule appropriately.) Thus, this term is integrable against any Gaussian measure. Now consider the expression  $(\int_0^T \frac{a}{\sqrt{2\pi D}} \frac{1}{t^{\frac{3}{2}}} e^{-\frac{a^2}{2Dt}} dt)^{-1}$  in the first term on the right hand side of (4.1). It is known from the reflection principle [16, 25] that

$$(5.13) \quad \int_0^T \frac{a}{\sqrt{2\pi D}} \frac{1}{t^{\frac{3}{2}}} e^{-\frac{a^2}{2Dt}} dt = \int_a^\infty \frac{e^{-\frac{x^2}{2DT}}}{\sqrt{2\pi DT}} dx = 2 \int_{\frac{a}{\sqrt{DT}}}^\infty \frac{e^{-\frac{y^2}{2}}}{\sqrt{2\pi}} dy.$$

It is well-known and can be proved by l'Hôpital's rule that  $\int_x^\infty e^{-\frac{y^2}{2}} dy \sim \frac{1}{x} e^{-\frac{x^2}{2}}$  as  $x \rightarrow \infty$ . From this it follows that

$$\left( \int_0^T \frac{a}{\sqrt{2\pi D}} \frac{1}{t^{\frac{3}{2}}} e^{-\frac{a^2}{2Dt}} dt \right)^{-1} \sim \frac{\sqrt{2\pi} a}{2\sqrt{DT}} e^{\frac{a^2}{2DT}}, \text{ as } a \rightarrow \infty.$$

From these facts, it follows that (1.11) is finite if and only if  $T > \frac{\sigma^2}{D}$ .

From now on, we assume that  $T > \frac{\sigma^2}{D}$ . From (4.1), in order to prove the theorem, we need to evaluate  $\int_0^\infty \left( \int_0^T \frac{a}{\sqrt{2\pi D}} \frac{1}{t^{\frac{3}{2}}} e^{-\frac{a^2}{2Dt}} dt \right)^{-1} \frac{2}{\sqrt{2\pi}\sigma} e^{-\frac{a^2}{2\sigma^2}} da$

and  $\int_0^\infty \left( \frac{\int_0^T \frac{1}{t^{\frac{3}{2}}} e^{-\frac{a^2}{2Dt}} dt}{\int_0^T \frac{1}{t^{\frac{3}{2}}} e^{-\frac{a^2}{2Dt}} dt} \right) \frac{2}{\sqrt{2\pi}\sigma} e^{-\frac{a^2}{2\sigma^2}} da$ . Consider the latter term. Making the substitutions  $a = \sigma x$  and  $T = \frac{\sigma^2}{D} \mathcal{T}$ , we have

$$(5.14) \quad \int_0^\infty \left( \frac{\int_0^T \frac{1}{t^{\frac{3}{2}}} e^{-\frac{a^2}{2Dt}} dt}{\int_0^T \frac{1}{t^{\frac{3}{2}}} e^{-\frac{a^2}{2Dt}} dt} \right) \frac{2}{\sqrt{2\pi}\sigma} e^{-\frac{a^2}{2\sigma^2}} da = \int_0^\infty \frac{\int_0^{\frac{\sigma^2}{D} \mathcal{T}} \frac{1}{t^{\frac{3}{2}}} e^{-\frac{\sigma^2 x^2}{2Dt}} dt}{\int_0^{\frac{\sigma^2}{D} \mathcal{T}} \frac{1}{t^{\frac{3}{2}}} e^{-\frac{\sigma^2 x^2}{2Dt}} dt} \frac{2}{\sqrt{2\pi}} e^{-\frac{x^2}{2}} dx.$$

Making the substitution  $t = \frac{\sigma^2}{D} s$ , we have

$$(5.15) \quad \int_0^\infty \frac{\int_0^{\frac{\sigma^2}{D} \mathcal{T}} \frac{1}{t^{\frac{3}{2}}} e^{-\frac{\sigma^2 x^2}{2Dt}} dt}{\int_0^{\frac{\sigma^2}{D} \mathcal{T}} \frac{1}{t^{\frac{3}{2}}} e^{-\frac{\sigma^2 x^2}{2Dt}} dt} \frac{2}{\sqrt{2\pi}} e^{-\frac{x^2}{2}} dx = \frac{\sigma^2}{D} \left( \frac{2}{\sqrt{2\pi}} \int_0^\infty \frac{\int_0^{\mathcal{T}} \frac{1}{s^{\frac{3}{2}}} e^{-\frac{x^2}{2s}} ds}{\int_0^{\mathcal{T}} \frac{1}{s^{\frac{3}{2}}} e^{-\frac{x^2}{2s}} ds} e^{-\frac{x^2}{2}} dx \right).$$

Making the same series of substitutions in the other integral that we need to evaluate, we obtain

$$(5.16) \quad \int_0^\infty \left( \int_0^T \frac{a}{\sqrt{2\pi D} t^{\frac{3}{2}}} e^{-\frac{a^2}{2Dt}} dt \right)^{-1} \frac{2}{\sqrt{2\pi}\sigma} e^{-\frac{a^2}{2\sigma^2}} da = 2 \int_0^\infty \frac{1}{\int_0^{\mathcal{T}} \frac{x}{s^{\frac{3}{2}}} e^{-\frac{x^2}{2s}} ds} e^{-\frac{x^2}{2}} dx.$$

Now (1.12) follows from (4.1), (5.15) and (5.16). Making the substitution  $s = \frac{Dt}{\sigma^2}$  in (1.12) gives (1.11). We obtained (1.13) from (1.12) using the Desmos graphing calculator.  $\square$

## 6. PROOFS OF THEOREMS 4-6

*Proof of Theorem 4.* From (2.3) and the fact that  $E_0^{(3;r)} \tau_a = 0$ , for  $|a| \leq \epsilon_0$ , we have

$$(6.1) \quad \epsilon_0 \int_{\mathbb{R}^3} (E_0^{(3;r)} \tau_a) \mu_{\sigma^2}^{\text{Gauss},3}(da) = \frac{1}{r} \int_{a \in \mathbb{R}^3: |a| > \epsilon_0} (|a| e^{\sqrt{\frac{r}{D}}(|a| - \epsilon_0)} - \epsilon_0) \frac{e^{-\frac{|a|^2}{2\sigma^2}}}{(2\pi\sigma^2)^{\frac{3}{2}}} da.$$

Thus, the monotone convergence theorem gives

$$(6.2) \quad \lim_{\epsilon_0 \rightarrow 0} \epsilon_0 \int_{\mathbb{R}^3} (E_0^{(3;r)} \tau_a) \mu_{\sigma^2}^{\text{Gauss},3}(da) = \frac{1}{r} \int_{\mathbb{R}^3} |a| e^{\sqrt{\frac{r}{D}}|a|} \frac{e^{-\frac{|a|^2}{2\sigma^2}}}{(2\pi\sigma^2)^{\frac{3}{2}}} da.$$

Letting  $R = |a|$  and then letting  $x = \frac{R}{\sigma}$ , we have

$$(6.3) \quad \begin{aligned} \frac{1}{r} \int_{\mathbb{R}^3} |a| e^{\sqrt{\frac{r}{D}}|a|} \frac{e^{-\frac{|a|^2}{2\sigma^2}}}{(2\pi\sigma^2)^{\frac{3}{2}}} da &= \frac{1}{r} \int_0^\infty R e^{\sqrt{\frac{r}{D}}R} \frac{e^{-\frac{R^2}{2\sigma^2}}}{(2\pi\sigma^2)^{\frac{3}{2}}} 4\pi R^2 dR = \\ &= \frac{2\sigma}{\sqrt{2\pi} r} \int_0^\infty x^3 e^{\sqrt{\frac{r}{D}}\sigma x} e^{-\frac{x^2}{2}} dx. \end{aligned}$$

Letting  $s = \sigma^2 \frac{r}{D}$ , we obtain

$$(6.4) \quad \frac{2\sigma}{\sqrt{2\pi} r} \int_0^\infty x^3 e^{\sqrt{\frac{r}{D}}\sigma x} e^{-\frac{x^2}{2}} dx = \frac{\sigma^3}{D} \left( \frac{2}{\sqrt{2\pi}s} \int_0^\infty x^3 e^{\sqrt{s}x} e^{-\frac{x^2}{2}} dx \right).$$

Now (1.14) follows from (6.2) and (6.3), and (1.15) follows from (6.2)-(6.4). Finally, (1.16) follows from (1.15) using the Desmos graphing calculator.  $\square$

*Proof of Theorem 5.* From the monotone convergence theorem, it follows that  $\lim_{\epsilon_0 \rightarrow 0} \int_{\{a \in \mathbb{R}^3 : |a| > \epsilon_0\}} e^{\frac{2(|a| - \epsilon_0)^2}{DT}} \mu_{\sigma^2}^{\text{Gauss},3}(da) = \infty$ , if  $T \leq \frac{4\sigma^2}{D}$ . Thus, from the second line of (3.10), it follows that

$$(6.5) \quad \lim_{\epsilon_0 \rightarrow 0} \epsilon_0 \int_{\mathbb{R}^3} (E_0^{\text{bb},3;T} \tau_a) \mu_{\sigma^2}^{\text{Gauss},3}(da) = \infty, \text{ if } T \leq \frac{4\sigma^2}{D}.$$

From now on, we assume that  $T > \frac{4\sigma^2}{D}$ . From (3.10) and (3.11), we have

$$(6.6) \quad \lim_{\epsilon_0 \rightarrow 0} \epsilon_0 E_0^{\text{bb},3;T} \tau_a = \frac{T}{2} |a| e^{\frac{2|a|^2}{TD}}, \text{ for all } 0 \neq a \in \mathbb{R}^3.$$

From (6.6) along with the first line in (3.10) and (3.11), it follows from the dominated convergence theorem that

$$(6.7) \quad \lim_{\epsilon_0 \rightarrow 0} \epsilon_0 \int_{\mathbb{R}^3} (E_0^{\text{bb},3;T} \tau_a) \mu_{\sigma^2}^{\text{Gauss},3}(da) = \frac{T}{2} \int_{\mathbb{R}^3} |a| e^{\frac{2|a|^2}{TD}} \frac{e^{-\frac{|a|^2}{2\sigma^2}}}{(2\pi\sigma^2)^{\frac{3}{2}}} da.$$

We have  $\frac{2|a|^2}{TD} - \frac{|a|^2}{2\sigma^2} = -(\frac{TD-4\sigma^2}{TD\sigma^2}) \frac{|a|^2}{2}$ . Thus,

$$(6.8) \quad \int_{\mathbb{R}^3} |a| e^{\frac{2|a|^2}{TD}} e^{-\frac{|a|^2}{2\sigma^2}} da = \int_{\mathbb{R}^3} |a|^2 e^{-\frac{|a|^2}{2} \left( \frac{TD-4\sigma^2}{TD\sigma^2} \right)} da = \int_0^\infty R e^{-\frac{R^2}{2} \left( \frac{TD-4\sigma^2}{TD\sigma^2} \right)} 4\pi R^2 dR.$$

Integrating by parts yields

$$(6.9) \quad \int_0^\infty R e^{-\frac{R^2}{2} \left( \frac{TD-4\sigma^2}{TD\sigma^2} \right)} 4\pi R^2 dR = 8\pi \left( \frac{TD\sigma^2}{TD-4\sigma^2} \right)^2, \quad T > \frac{4\sigma^2}{D}.$$

Now (1.17) follows from (6.5)-(6.9), (1.18) follows immediately from (1.17) and (1.19) is obtained using the Desmos graphing calculator.  $\square$

*Proof of Theorem 6.* Considering (4.5), a proof similar to that given for the corresponding result in the one-dimensional case shows that the left hand side of (1.20) is finite if and only if  $T > \frac{\sigma^2}{D}$ .



From now on, we assume that  $T > \frac{\sigma^2}{D}$ . Using the dominated convergence theorem for the first term on the right hand side of (4.5) and the bounded convergence theorem for the second term there, and recalling that  $E_0^{3;T} \tau_a = 0$ , for  $|a| \leq \epsilon_0$ , we obtain

$$(6.10) \quad \lim_{\epsilon_0 \rightarrow 0} \epsilon_0 \int_{\mathbb{R}^3} (E_0^{(3;T)} \tau_a) \mu_{\sigma^2}^{\text{Gauss},3}(da) = T \int_{\mathbb{R}^3} \frac{1}{\int_0^T \frac{1}{\sqrt{2\pi D}} \frac{1}{t^{\frac{3}{2}}} e^{-\frac{|a|^2}{2Dt}} dt} \frac{e^{-\frac{|a|^2}{2\sigma^2}}}{(2\pi\sigma^2)^{\frac{3}{2}}} da.$$

We have

$$(6.11) \quad \int_{\mathbb{R}^3} \frac{1}{\int_0^T \frac{1}{\sqrt{2\pi D}} \frac{1}{t^{\frac{3}{2}}} e^{-\frac{|a|^2}{2Dt}} dt} \frac{e^{-\frac{|a|^2}{2\sigma^2}}}{(2\pi\sigma^2)^{\frac{3}{2}}} da = \int_0^\infty \frac{1}{\int_0^T \frac{1}{\sqrt{2\pi D}} \frac{1}{t^{\frac{3}{2}}} e^{-\frac{R^2}{2Dt}} dt} \frac{e^{-\frac{R^2}{2\sigma^2}}}{(2\pi\sigma^2)^{\frac{3}{2}}} 4\pi R^2 dR.$$

Making the substitutions  $R = x\sigma$  and  $T = \frac{\sigma^2}{D}\mathcal{T}$ , we have

$$(6.12) \quad \int_0^\infty \frac{1}{\int_0^T \frac{1}{\sqrt{2\pi D}} \frac{1}{t^{\frac{3}{2}}} e^{-\frac{R^2}{2Dt}} dt} \frac{e^{-\frac{R^2}{2\sigma^2}}}{(2\pi\sigma^2)^{\frac{3}{2}}} 4\pi R^2 dR = \int_0^\infty \frac{1}{\int_0^{\frac{\sigma^2}{D}\mathcal{T}} \frac{1}{\sqrt{2\pi D}} \frac{1}{t^{\frac{3}{2}}} e^{-\frac{\sigma^2 x^2}{2Dt}} dt} \frac{e^{-\frac{x^2}{2}}}{(2\pi)^{\frac{3}{2}}} 4\pi x^2 dx.$$

Making the substitution  $t = \frac{\sigma^2}{D}s$ , we have

$$(6.13) \quad \int_0^\infty \frac{1}{\int_0^{\frac{\sigma^2}{D}\mathcal{T}} \frac{1}{\sqrt{2\pi D}} \frac{1}{t^{\frac{3}{2}}} e^{-\frac{\sigma^2 x^2}{2Dt}} dt} \frac{e^{-\frac{x^2}{2}}}{(2\pi)^{\frac{3}{2}}} 4\pi x^2 dx = 2\sigma \int_0^\infty \frac{1}{\int_0^{\mathcal{T}} \frac{1}{\sqrt{2\pi D}} \frac{1}{s^{\frac{3}{2}}} e^{-\frac{x^2}{2s}} ds} x^2 e^{-\frac{x^2}{2}} dx.$$

From (6.10)-(6.13), we obtain (1.21). Making the substitution  $s = \frac{Dt}{\sigma^2}$  in (1.21) gives (1.20). We obtained (1.22) from (1.21) using the Desmos graphic calculator.

□

## 7. PROOF OF THEOREM 7

From (2.2), we have

$$(7.1) \quad E_0^{2;r} \tau_a = \frac{1}{r} \left( \frac{K_0(\sqrt{\frac{r}{D}} \epsilon_0)}{K_0(\sqrt{\frac{r}{D}} |a|)} - 1 \right), \quad |a| > \epsilon_0.$$

One has the asymptotic formula  $K_0(x) \sim -\log \frac{x}{2}$  as  $x \rightarrow 0$  [27, p.80]. Thus,

$$(7.2) \quad \lim_{\epsilon_0 \rightarrow 0} \frac{1}{|\log \epsilon_0|} E_0^{2;r} \tau_a = \frac{1}{r K_0(\sqrt{\frac{r}{D}} |a|)}.$$

From the above asymptotic behavior,  $\frac{1}{K_0(\sqrt{\frac{r}{D}} |a|)}$  is integrable in a neighborhood of  $0 \in \mathbb{R}$ . Also,  $K_0(x)$  decays exponentially as  $x \rightarrow \infty$  [27, p.202].

Therefore,  $\frac{1}{K_0(\sqrt{\frac{r}{D}}|a|)}$  is integrable against any Gaussian density. Using these facts with (7.2) and the dominated convergence theorem, and recalling that  $E_0^{2;r}\tau_a = 0$ , for  $|a| \leq \epsilon_0$ , we obtain

$$(7.3) \quad \lim_{\epsilon \rightarrow 0} \frac{1}{|\log \epsilon_0|} \int_{\mathbb{R}^2} (E^{2;r}\tau_a) \mu_{\sigma^2}^{\text{Gauss},2}(da) = \frac{1}{r} \int_{\mathbb{R}^2} \frac{1}{K_0(\sqrt{\frac{r}{D}}|a|)} \frac{e^{-\frac{|a|^2}{2\sigma^2}}}{2\pi\sigma^2} da.$$

We have

$$(7.4) \quad \int_{\mathbb{R}^2} \frac{1}{K_0(\sqrt{\frac{r}{D}}|a|)} \frac{e^{-\frac{|a|^2}{2\sigma^2}}}{2\pi\sigma^2} da = \int_0^\infty \frac{1}{K_0(\sqrt{\frac{r}{D}}R)} \frac{e^{-\frac{R^2}{2\sigma^2}}}{\sigma^2} R dR.$$

Making the change of variables,  $R = \sigma x$ , we have

$$(7.5) \quad \int_0^\infty \frac{1}{K_0(\sqrt{\frac{r}{D}}R)} \frac{e^{-\frac{R^2}{2\sigma^2}}}{\sigma^2} R dR = \int_0^\infty \frac{1}{K_0(\sqrt{\frac{r}{D}}\sigma x)} x e^{-\frac{x^2}{2}} dx.$$

Now (1.23) follows from (7.3)–(7.5). One obtains (1.24) from (1.23) by substituting  $r = \frac{D}{\sigma^2}s$ . We obtained (1.25) from (1.24), using the Desmos graphing calculator and using the representation  $K_0(x) = \int_0^\infty e^{-x \cosh t} dt$  [27, p.181].  $\square$

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